

Cherish every Joule: Maximizing throughput with an eye on network-wide energy consumption

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Abstract

Conserving network-wide energy consumption is becoming an increasingly important concern for network operators. In this work, we study network-wide energy conservation problem which we hope will offer insights to both network operators and users. In the first part of this work, we study how to maximize throughput under a network-wide energy constraint. We formulate this problem as a mixed-integer nonlinear program (MINLP). We propose a novel piece-wise linear approximation to transform the nonlinear constraints into linear constraints. We prove that the solution developed under this approach is near-optimal with guaranteed performance bound. In the second part, we generalize the problem in the first part by exploring throughput and network-wide energy optimization via a multicriteria optimization framework. We show that the weakly Pareto-optimal points in the solution can characterize an optimal throughput-energy curve. We offer some interesting properties of the optimal throughput-energy curve which are useful to both network operators and end users.

Keywords

Network-wide energy, network throughput, optimization, multicriteria optimization, multi-hop wireless networks

1 Introduction

With the proliferation of wireless networks, the concern of energy consumption is becoming increasingly important for network operators. Conserving network-wide energy consumption not only can help reducing CO₂ emissions and protect the environment, but also can significantly reduce the operating cost for network providers. Since energy-related operating cost is directly tied to *network-wide* energy consumption, it is critical to study network optimization problems with an eye on total network-wide energy consumption.

In this paper, we study network-wide energy conservation problem in a multi-hop wireless network which we hope will offer insights to both network operators and end users. Specifically, in the first part of this work, we will show how to maximize network throughput under a given network-wide total energy consumption budget. This may correspond to a scenario where a network operator has a budget on total energy consumption. In the second part, we generalize the problem in the first part by studying how to optimize both network throughput and network-wide energy consumption through a multicriteria optimization framework. This allows us to characterize the trend of throughput when the total energy consumption budget changes.

We recognize that there is a wealth of literature on optimizing network throughput with energy considerations. A major branch of these prior efforts followed various heuristic approaches in developing physical, link, and network layer schemes and algorithms (see, e.g., [20, 22]). This is in contrast to our work in this paper, which follows a formal optimization framework with the goal of offering performance guarantee of the final solution.

Within the branch of related work that followed formal optimization framework in studying network throughput maximization with energy consideration (see, e.g., [8, 19]), we find that most of these works only considered per-link power constraint or per-node power constraint. Although these constraints are important to characterize local energy consumption, it is not clear how to extend results for local link/node energy conservation to *network-wide* energy conservation, due to the complex inter-dependencies among the layers. Therefore, these prior results cannot directly benefit network operators, who are more concerned with total network-wide energy consumption.

Our work is complementary to a branch of previous work that addressed how to minimize network-wide energy consumption while satisfying some traffic demands (see, e.g., [14, 17]). These works are orthogonal to the problem that we shall study in the first part of this paper. It will soon be clear that our mathematical formulation and proposed solution differ from all these seemingly similar efforts. Further, in the second part of this paper, we consider joint optimization of throughput and network-wide energy, which explores the domain of multi-criteria optimization that is not well studied in the wireless networking community. In our recent work in [11], we explored multicriteria optimization of network energy and throughput. However, power control was not considered in [11]. In this work, we shall consider power control at each node, which is more

interesting.

The main contributions of this paper are the following:

- First, we study how to maximize network throughput under a total network-wide energy consumption constraint. We show that this problem involves both network and physical layer variables and can be formulated as a mixed-integer nonlinear program (MINLP). To solve this problem efficiently, we propose a novel piece-wise linear approximation to transform the nonlinear constraints into linear constraints. We prove that the solution developed under this linear approximation is near-optimal in the sense that the performance gap between our solution and the optimal solution (despite unknown) can be made arbitrary narrow depending on required accuracy.
- Second, we generalize the problem in the first part by exploring joint optimization of both network throughput and network energy consumption via a multicriteria optimization framework, i.e., *maximizing* network throughput while *minimizing* network-wide energy consumption. We find that all the weakly Pareto-optimal points characterize an optimal throughput-energy curve. This curve shows how the maximum network throughput changes as total network-wide energy budget changes. We offer some interesting properties of this optimal throughput-energy curve that are useful to both network operators and end users.

The remainder of this paper is organized as follows. In Section 2, we describe our network model. In Section 3, we study how to maximize network throughput under a given total network-wide energy budget. In Section 4, we study how to optimize both network throughput and energy under a multicriteria framework. Section 5 presents some numerical results that illustrate our theoretical findings. Section 6 concludes this paper.

2 Network Model

Consider a multi-hop wireless ad hoc network, represented by a directed graph $\mathcal{G} = \{\mathcal{N}, \mathcal{L}\}$, where \mathcal{N} and \mathcal{L} are the sets of nodes and directional links, respectively. A link between two nodes exists if and only if the distance between the two is within a certain transmission range. If two nodes are not within one-hop of each other, then a node has to resort to multi-hop to relay messages. We

Table 1: Notation.

Symbol	Definition
B_l	Channel bandwidth on link l
c_l	Capacity of link l
d_l	Distance between link l 's transmitting node and receiving node
$d(f)$	Destination node of session $f \in \mathcal{F}$
\mathcal{F}	The set of user sessions in the network
h_l	Channel gain on link l
\mathcal{L}	The set of links in the network
$\mathcal{L}_i^{\text{In}}$	The set of incoming links at node i
$\mathcal{L}_i^{\text{Out}}$	The set of outgoing links at node i
\mathcal{N}	The set of nodes in the network
p_l	Transmission power of link l
P_d	The circuits power consumption of an active link
P	$= \sum_{l \in \mathcal{L}} (p_l + y_l P_d)$, network-wide energy consumption rate
P_{net}	Network-wide energy budget
$r(f)$	Data rate of session $f \in \mathcal{F}$
$r_l(f)$	Data rate on link l that is attributed to session f
$s(f)$	Source node of session f
U	$= \sum_{m \in \mathcal{M}} w(f)r(f)$, the network throughput
$w(f)$	A weight assigned to session $f \in \mathcal{F}$
y_l	A binary variable indicating whether or not link l is active
η	Ambient Gaussian noise density

assume orthogonal channels on all links (similar to that in [2, 13, 15]). This can be done by some interference avoidance mechanism (e.g., OFDMA). Note that orthogonal channels do not require as many channels as the number of active links in the network since one can reuse channels on links that are spatially far away from each other. This is called spatial reuse and is commonly used in wireless networks to improve channel efficiency. Note that designing a channel assignment algorithm to achieve orthogonality has been well studied in the literature and its discussion is beyond the scope of this paper.

We assume there is a set of \mathcal{F} active (unicast) communication sessions in the network. Denote $s(f)$ and $d(f)$ the source and destination nodes of session $f \in \mathcal{F}$, respectively. To differentiate the importance of these user sessions, each session f is assigned a weight $w(f)$. Denote $r(f)$ the data rate of session f . The network throughput U in this paper is represented by the sum of weighted session rates, which is $\sum_{f \in \mathcal{F}} w(f) \cdot r(f)$. Table 1 lists all the notation in this paper.

2.1 Energy Consumption and Power Control

When a wireless link is active for communications, its energy consumption includes transmission power and device power [4, 16], where transmission power is for data transmission over a distance and device power is consumed by device electronics for encoding, modulation, decoding, demodulation, etc. Denote P_d as device power, which we assume is a constant if link is active. Denote p_l the transmission power on link l , which is a tunable (variable) system parameter.

Denote y_l a binary variable indicating whether or not link l is active, i.e.,

$$y_l = \begin{cases} 1 & \text{if link } l \text{ is active;} \\ 0 & \text{otherwise.} \end{cases}$$

The energy consumption rate of link l , including transmission power and device power, is $p_l + y_l P_d$.

Assume that the maximum transmission power of a node is P_{\max} . Then, we have the following relationship between p_l and y_l :

$$p_l \leq y_l \cdot P_{\max} \quad (l \in \mathcal{L}). \quad (1)$$

For all active links at a node, we have the following node-level transmission power constraint:

$$\sum_{l \in \mathcal{L}_i^{\text{Out}}} p_l \leq P_{\max} \quad (i \in \mathcal{N}), \quad (2)$$

where $\mathcal{L}_i^{\text{Out}}$ is the set of potential outgoing links at node i .

Denote P as the total energy consumption rate on all active links in the network. Then, the network-wide energy consumption rate P can be written as $P = \sum_{l \in \mathcal{L}} (p_l + y_l P_d)$.

2.2 Routing and Link Capacity

To transport data from a source node to its destination node that is more than one-hop away, multi-hop relaying is necessary. Since single-path flow routing is overly restrictive and is unlikely to offer optimal solution, we allow flow splitting so that data can be delivered on multi-path routes. We model multi-path flow routing as follows. Denote $r_l(f)$ the amount of flow rate on link l that is attributed to session $f \in \mathcal{F}$. Denote $\mathcal{L}_i^{\text{In}}$ the set of potential incoming links at node i . If node i

is the source node of session f , i.e., $i = s(f)$, then

$$\sum_{l \in \mathcal{L}_i^{\text{Out}}} r_l(f) = r(f). \quad (3)$$

If node i is an intermediate relay node of session f , i.e., $i \neq s(f)$ and $i \neq d(f)$, then

$$\sum_{l \in \mathcal{L}_i^{\text{Out}}} r_l(f) = \sum_{m \in \mathcal{L}_i^{\text{In}}} r_m(f). \quad (4)$$

If node i is the destination node of session f , i.e., $i = d(f)$, then

$$\sum_{l \in \mathcal{L}_i^{\text{In}}} r_l(f) = r(f). \quad (5)$$

It can be easily verified that if (3) and (4) are satisfied, then (5) must be satisfied. As a result, it is sufficient to list only (3) and (4) in the formulation.

Under the above flow routing scheme, the aggregate flow rate at link l is $\sum_{f \in \mathcal{F}} r_l(f)$. Since aggregate flow rate on any link cannot exceed the link's capacity, we have the following link capacity constraint:

$$\sum_{f \in \mathcal{F}} r_l(f) \leq c_l \quad (l \in \mathcal{L}), \quad (6)$$

where c_l is the capacity on link l . Given that we are employing orthogonal channels among the links in the network, we have:

$$c_l = B_l \log_2 \left(1 + \frac{p_l \cdot h_l}{\eta B_l} \right), \quad (7)$$

where B_l is the bandwidth of link l under a given channel assignment, h_l is channel gain between the transmitter and receiver of link l and η is the ambient Gaussian noise density. Combining (6) and (7), we have:

$$\sum_{f \in \mathcal{F}} r_l(f) \leq B_l \log_2 \left(1 + \frac{p_l \cdot h_l}{\eta B_l} \right) \quad (l \in \mathcal{L}). \quad (8)$$

Note that constraint (8) couples network flow variables (i.e., $r_l(f)$) and physical layer power variable p_l .

3 Throughput Maximization Under Network-wide Energy Constraint

In this section, we study how to maximize network throughput under a given network-wide energy budget. This problem is motivated by the scenario where we have a strict total energy consumption limit in the network (e.g., due to a given operating budget on energy). The question that we pose is: Given the network-wide energy operating budget P_{net} , i.e.,

$$P = \sum_{l \in \mathcal{L}} (p_l + y_l P_d) \leq P_{\text{net}}, \quad (9)$$

how to adjust the power on each link and multi-path routing for each session so that the maximum network throughput is achieved?

Mathematically, this problem can be formulated as follows:

$$\begin{aligned} \mathbf{OPT:} \quad & \max \quad U = \sum_{f \in \mathcal{F}} w(f)r(f) \\ & \text{s.t.} \quad \text{Constraints (1), (2), (3), (4), (8), (9)} \\ & \quad \text{Variables } y_l \in \{0, 1\}, p_l, r_l(f), r(f) \geq 0 \quad (l \in \mathcal{L}, f \in \mathcal{F}), \end{aligned}$$

where y_l is a binary variable, p_l , $r(f)$ and $r_l(f)$ are continuous variables and all the other parameters are constants. OPT is a mixed-integer nonlinear program (MINLP), which in general is NP-hard [9]. Note that the network-wide energy constraint complicates overall problem by bringing in integer variables.

MINLP problems are known to be difficult due to the combinatorial nature of mixed integer programs and the difficulty in solving nonlinear programs. Note that there exist some techniques to address *general* MINLP problems (e.g., outer approximation methods [6], branch-and-bound [7], extended cutting plane methods [21], and generalized Benders' decomposition [10]). But these techniques do not exploit our problem-specific structures and properties, and hence can only handle small-size problems.

In this paper, we exploit the structure of our MINLP problem and develop a novel near-optimal solution with performance guarantee. Note that in OPT's formulation, the only set of nonlinear

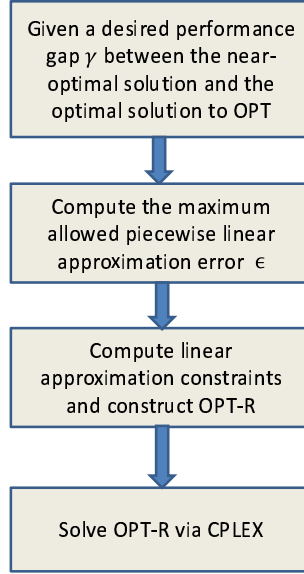


Figure 1: A flow chart to develop a near-optimal solution to OPT.

constraints are the link capacity constraints in (8), which involve the log function. To address this problem, we propose a piece-wise linear approximation technique to transform the nonlinear constraints to linear constraints. Our main idea is as follows. We first use a set of linear segments to approximate the log term in (8) and guarantee the linear approximation error will not exceed a threshold ϵ . Subsequently, the nonlinear constraints in OPT are replaced by a set of linear constraints. Denote the linearized optimization problem as OPT-R, which is a MILP problem. Since MILP problems are much easier than MINLP problems, we can apply a solver such as CPLEX [3] to obtain a solution efficiently.

We will show that solving OPT-R can give us a near-optimal solution to the original problem OPT. Denote γ as desired performance gap of our near-optimal solution, i.e., the difference in the objective values between the optimal solution and the near-optimal solution to OPT. We analyze the relationship between performance gap γ and the linear approximation error ϵ (see details in Section 3.2). Specifically, for a desired performance gap γ , we compute the maximum allowed linear approximation error ϵ . After obtaining ϵ , we can compute the linear approximation constraints and construct OPT-R (see details in Section 3.1). Solving the OPT-R will give us a near-optimal solution with performance guarantee γ . We summarize the above steps in Fig. 1. In the rest of this section, we fill in the details of these steps.

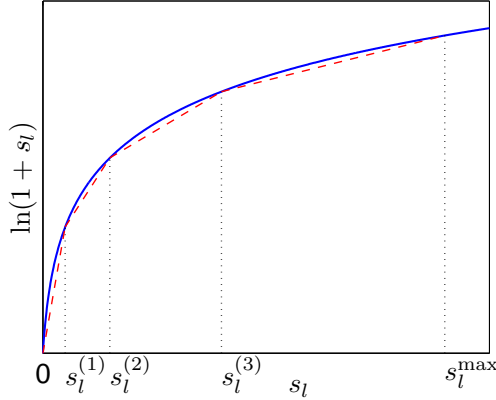


Figure 2: An illustration of piece-wise linear approximation with four linear segments.

3.1 Piece-wise Linear Approximation

The nonlinear constraint in (8) can be written as

$$\sum_{f \in \mathcal{F}} r_l(f) \leq \frac{B_l}{\ln 2} \ln\left(1 + \frac{p_l \cdot h_l}{\eta B_l}\right). \quad (10)$$

To simplify notation, denote

$$s_l = \frac{p_l h_l}{\eta B_l}. \quad (11)$$

Then, the nonlinear term in (10) can be written as $\ln(1 + s_l)$. The range of s_l is $[0, s_l^{\max}]$, with $s_l^{\max} = (P_{\max} h_l) / (\eta B_l)$. Our piece-wise linear approximation is to use a set of consecutive linear segments to approximate $\ln(1 + s_l)$ for $s_l \in [0, s_l^{\max}]$ (see Fig. 2). Denote ϵ the maximum allowed error of this linear approximation. Denote K_l the number of linear segments that is needed to meet this error requirement. (K_l will be determined later.) Denote $s_{l,0}, s_{l,1}, \dots, s_{l,K_l}$ the X -axis values of the endpoints of these K segments, with $s_{l,0} = 0$ and $s_{l,K_l} = s_l^{\max}$.

A naive approach to generate a linear approximation is making $s_l^{(k)}, k = 0, \dots, K_l$, evenly distributed between $[0, s_l^{\max}]$. When setting K_l sufficiently large, the linear approximation error requirement will be satisfied. Although this approach is straightforward and easy to implement, it will generate too many linear segments to approximate $\ln(1 + s_l)$. Note that the derivative of curve $\ln(1 + s_l)$ decreases as s_l increases. This motivates us to enlarge the size of an interval

as s_l increases. Thus, we want to pursue an algorithm that optimally divides the K_l intervals within $[0, s_l^{\max}]$. By “optimally”, we refer to finding the *minimum* K_l such that the maximum approximation error of each line segment is no more than ϵ .

Denote $m_l^{(k)}$ as the slope of the k -th linear segment, i.e.,

$$m_l^{(k)} = \frac{\ln(1 + s_l^{(k)}) - \ln(1 + s_l^{(k-1)})}{s_l^{(k)} - s_l^{(k-1)}}. \quad (12)$$

Denote $g_l^{(k)}(s_l)$ as the k -th linear approximation segment (see Fig. 3), which can be represented as follows:

$$g_l^{(k)}(s_l) = m_l^{(k)} \cdot (s_l - s_l^{(k-1)}) + \ln(1 + s_l^{(k-1)}), \text{ for } s_l^{(k-1)} \leq s_l \leq s_l^{(k)}. \quad (13)$$

Our algorithm computes the values of $s_l^{(0)}, \dots, s_l^{(K_l)}$ sequentially (for a given ϵ) based on Algorithm 1 as follows.

Algorithm 1 *Initialization:* $k := 0$ and $s_l^{(0)} := 0$.

1. $k := k + 1$.

2. Compute $m_l^{(k)}$ satisfying

$$-\ln(m_l^{(k)}) + m_l^{(k)}(1 + s_l^{(k-1)}) - 1 - \ln(1 + s_l^{(k-1)}) = \epsilon. \quad (14)$$

3. After obtaining $m_l^{(k)}$, compute $s_l^{(k)}$ satisfying (12).

4. If $s_l^{(k)} < s_l^{\max}$, go back to Step 1.

5. $K_l := k$; $s_l^{(K_l)} := s_l^{\max}$.

6. Update $m_l^{(K_l)}$ using (12).

The values of $m_l^{(k)}$ in (14) and $s_l^{(k)}$ in (12) can be solved by numerical methods such as bisection method or Newton’s method [18, Chapter 2].

Our linear approximation method (Algorithm 1) satisfies the linear approximation error requirement with the minimum number of linear segments to approximate $\ln(1 + s_l)$ for $s_l \in [0, s_l^{\max}]$.

We formalize these two claims in the following two lemmas.

Lemma 1 For the piece-wise linear approximation generated by Algorithm 1, the maximum approximation error of each linear segment is at most ϵ .

Proof Denote $\epsilon_l^{(k)}$ the maximum linear approximation error for the k -th linear segment, i.e.,

$$\epsilon_l^{(k)} = \max_{s_l^{(k-1)} \leq s_l \leq s_l^{(k)}} \left| \ln(1 + s_l) - g_l^{(k)}(s_l) \right| = \max_{s_l^{(k-1)} \leq s_l \leq s_l^{(k)}} \left\{ \ln(1 + s_l) - g_l^{(k)}(s_l) \right\},$$

where the equality holds since $\ln(1 + s_l)$ is a convex function of s_l and all linear segments lie beneath the $\ln(1 + s_l)$ curve.

Consider the k -th linear segment. Referring to Fig. 3, we can move $g_l^{(k)}(s_l)$ upward until it is tangential to the $\ln(1 + s_l)$ curve. It is easy to see that the tangential point achieves the maximum approximation error $\epsilon_l^{(k)}$. Denote $\hat{s}_l^{(k)}$ the X -axis value of that tangential point. Since the derivative of $\ln(1 + s_l)$ is $\frac{1}{1+s_l}$, we have $\frac{1}{1+\hat{s}_l^{(k)}} = m_l^{(k)}$, i.e.,

$$\hat{s}_l^{(k)} = \frac{1}{m_l^{(k)}} - 1, \quad (15)$$

where $m_l^{(k)}$ is slope of linear segment $g_l^{(k)}(s_l)$. Therefore, the maximum approximation error $\epsilon_l^{(k)}$ can be written as

$$\begin{aligned} \epsilon_l^{(k)} &= \ln(1 + \hat{s}_l^{(k)}) - g_l^{(k)}(\hat{s}_l^{(k)}) = \ln(1 + \hat{s}_l^{(k)}) - [m_l^{(k)} \cdot (\hat{s}_l^{(k)} - s_l^{(k-1)}) + \ln(1 + s_l^{(k-1)})] \\ &= \ln \left(1 + \frac{1}{m_l^{(k)}} - 1 \right) - \left\{ m_l^{(k)} \cdot \left[\frac{1}{m_l^{(k)}} - 1 - s_l^{(k-1)} \right] + \ln(1 + s_l^{(k-1)}) \right\} \\ &= -\ln(m_l^{(k)}) + m_l^{(k)}(1 + s_l^{(k-1)}) - 1 - \ln(1 + s_l^{(k-1)}), \end{aligned}$$

where the second equality holds due to (13) and the third equality holds due to (15).

In Algorithm 1, we set $-\ln(m_l^{(k)}) + m_l^{(k)}(1 + s_l^{(k-1)}) - 1 - \ln(1 + s_l^{(k-1)}) = \epsilon$. Thus, the maximum linear approximation error for the k -th linear segment is ϵ . This result holds for all $k = 1, \dots, K_l$. This completes the proof. \square

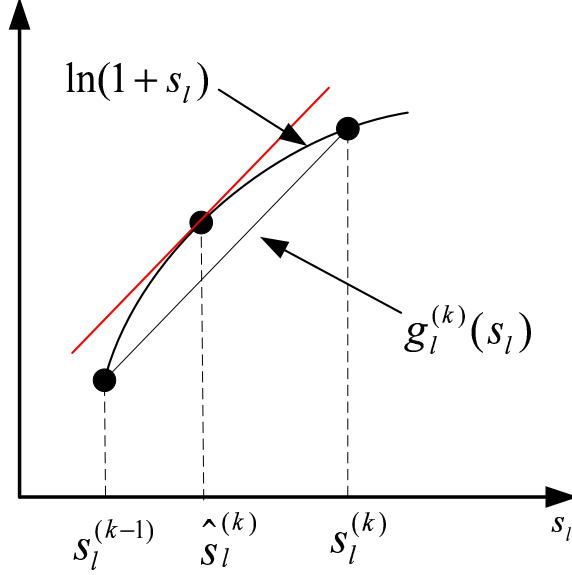


Figure 3: An illustration of the maximum approximation error for the k -th linear segment.

Lemma 2 For a given approximation error bound ϵ for each linear segment, the number of linear segments to approximate $\ln(1 + s_l)$ for $s_l \in [0, s_l^{\max}]$ is minimized by Algorithm 1.

The proof of Lemma 2 is given in the appendix.

With the proposed piece-wise linear approximation of $\ln(1 + s_l)$, constraint (8) can be replaced by the following set of constraints:

$$\sum_{f \in \mathcal{F}} r_l(f) \leq \frac{B_l}{\ln 2} g_l^{(k)}(s_l) \quad (k = 1, \dots, K_l, l \in \mathcal{L}),$$

where s_l and $g_l^{(k)}(s_l)$ are given in (11) and (13), respectively. Substituting (11) and (13) into the above equation, we have

$$\sum_{f \in \mathcal{F}} r_l(f) \leq \frac{B_l}{\ln 2} \left\{ m_l^{(k)} \left[\frac{p_l h_l}{\eta B_l} - s_l^{(k-1)} \right] + \ln \left[1 + s_l^{(k-1)} \right] \right\} \quad (k = 1, \dots, K_l, l \in \mathcal{L}). \quad (16)$$

By replacing the nonlinear constraints in (8) with the set of linear constraints in (16), we have a

revised formulation for OPT, which we denote as OPT-R.

$$\begin{aligned}
\mathbf{OPT-R:} \quad & \max \sum_{f \in \mathcal{F}} w(f)r(f) \\
& \text{s.t. Constraints (1), (2), (3), (4), (9), (16)} \\
& \text{Variables } y_l \in \{0, 1\}, p_l, r_l(f), r(f) \geq 0 \ (l \in \mathcal{L}, f \in \mathcal{F}) .
\end{aligned}$$

We have the following lemma on the relationship between OPT-R and OPT. Its proof is given in the appendix.

Lemma 3 *A feasible solution to OPT-R is a feasible solution to OPT.*

3.2 A Near-Optimal Solution

OPT-R is a mixed-integer linear program (MILP) and can be solved efficiently by CPLEX solver [3]. Now we give a bound for the gap between the optimal objective values of OPT and OPT-R, despite that the optimal objective value of OPT is unknown.

To proceed, we need the following notation. For a given power assignment (y_l, p_l) to OPT (i.e., satisfying constraints (1), (2), (9)), define $\bar{\mathbf{x}} = (\bar{r}(f), \bar{r}_l(f), y_l, p_l)$ as a feasible solution to OPT, where $(\bar{r}(f), \bar{r}_l(f))$ is the optimal solution to the following linear program (LP).

$$\begin{aligned}
\mathbf{OPT}(y_l, p_l): \quad & \max \sum_{f \in \mathcal{F}} w(f)r(f) \\
& \text{s.t. } \sum_{l \in \mathcal{L}_i^{\text{Out}}} r_l(f) = r(f) \quad (f \in \mathcal{F}, i \in \mathcal{N}, i = s(f)) \\
& \sum_{l \in \mathcal{L}_i^{\text{Out}}, l \neq (i, s(f))} r_l(f) = \sum_{l \in \mathcal{L}_i^{\text{In}}, l \neq (d(f), i)} r_l(f) \quad (f \in \mathcal{F}, i \in \mathcal{N}, i \neq s(f), d(f)) \\
& \sum_{f \in \mathcal{F}} r_l(f) \leq \bar{c}_l \quad (l \in \mathcal{L}) ,
\end{aligned}$$

where $\bar{c}_l = B_l \log_2(1 + \frac{p_l \cdot h_l}{\eta B_l})$. Note that $\mathbf{OPT}(y_l, p_l)$ is an LP once we set the power variables in OPT to values (y_l, p_l) .

For a feasible solution $\bar{\mathbf{x}} = (\bar{r}(f), \bar{r}_l(f), y_l, p_l)$ to OPT, we define a feasible solution $\mathbf{x}^\dagger = (r^\dagger(f), r_l^\dagger(f), y_l, p_l)$ to OPT-R as follows. In $\mathbf{x}^\dagger = (r^\dagger(f), r_l^\dagger(f), y_l, p_l)$, we let $(r^\dagger(f), r_l^\dagger(f))$ be the optimal flow routing solution to OPT-R with given (y_l, p_l) . That is, $(r^\dagger(f), r_l^\dagger(f))$ is the optimal solution to the following LP, in which the power variables in OPT-R are set to given values (y_l, p_l) .

$$\begin{aligned}
\mathbf{OPT-R}(y_l, p_l): \quad & \max \sum_{f \in \mathcal{F}} w(f)r(f) \\
\text{s.t.} \quad & \sum_{l \in \mathcal{L}_i^{\text{out}}} r_l(f) = r(f) && (f \in \mathcal{F}, i \in \mathcal{N}, i = s(f)) \\
& \sum_{l \in \mathcal{L}_i^{\text{out}}} r_l(f) = \sum_{l \in \mathcal{L}_i^{\text{in}}} r_l(f) && (f \in \mathcal{F}, i \in \mathcal{N}, i \neq s(f), d(f)) \\
& \sum_{f \in \mathcal{F}} r_l(f) \leq c_l^\dagger && (l \in \mathcal{L}),
\end{aligned}$$

where c_l^\dagger is a linear approximation of link l 's capacity under transmission power p_l .

Remark 1 Recall that we use constraints (16) to replace constraints (8) in OPT-R. When link l 's power is fixed at p_l , we can determine which line segment is involved in our linear approximation of $\ln(1 + s_l)$. Suppose the k -th linear segment is used, i.e., $s_l^{(k-1)} \leq \frac{p_l \cdot h_l}{\eta B_l} \leq s_l^{(k)}$. Then, link l 's approximated capacity can be written as $c_l^\dagger = \frac{B_l}{\ln 2} \cdot g_l^{(k)}(\frac{p_l \cdot h_l}{\eta B_l})$. \square

To quantify the performance gap between our solution to OPT-R and the optimal solution to OPT, we will first show that for any feasible power assignment (p_l, y_l) , the objective value gap between $\bar{\mathbf{x}}$ and \mathbf{x}^\dagger is at most $\epsilon \cdot \sum_{f \in \mathcal{F}} \sum_{l \in \mathcal{L}_{s(f)}^{\text{out}}} \frac{B_l}{\ln 2} w(f)$. Then, we will show that the gap between the optimal objective values of OPT and OPT-R is also bounded by $\epsilon \cdot \sum_{f \in \mathcal{F}} \sum_{l \in \mathcal{L}_{s(f)}^{\text{out}}} \frac{B_l}{\ln 2} w(f)$.

Lemma 4 For given (y_l, p_l) , denote \bar{z} and z^\dagger the objective values of solution $\bar{\mathbf{x}}$ (to OPT) and solution \mathbf{x}^\dagger (to OPT-R), respectively. Then we have $\bar{z} - z^\dagger \leq \epsilon \cdot \sum_{f \in \mathcal{F}} \sum_{l \in \mathcal{L}_{s(f)}^{\text{out}}} \frac{B_l}{\ln 2} w(f)$.

We find that it is not easy to characterize the gap between \bar{z} and z^\dagger directly. Since \bar{z} is the optimal value of $\text{OPT}(y_l, p_l)$ and z^\dagger is the optimal objective value of $\text{OPT-R}(y_l, p_l)$, we study the dual problems of $\text{OPT}(y_l, p_l)$ and $\text{OPT-R}(y_l, p_l)$ and quantify $\bar{z} - z^\dagger$ in the dual domain.

Proof Note that \bar{z} is the optimal objective value of $\text{OPT}(y_l, p_l)$ and z^\dagger is the optimal objective value of $\text{OPT-R}(y_l, p_l)$. Consider the dual problems of $\text{OPT}(y_l, p_l)$ and $\text{OPT-R}(y_l, p_l)$. Denote $\text{D}(y_l, p_l)$ and $\text{D-R}(y_l, p_l)$ as the dual problems of $\text{OPT}(y_l, p_l)$ and $\text{OPT-R}(y_l, p_l)$, respectively. Note that $\text{D}(y_l, p_l)$ and $\text{D-R}(y_l, p_l)$ will have the same constraints, but different objective functions.

Denote the dual variables corresponding to the first group of constraints in $\text{OPT}(y_l, p_l)$ and $\text{OPT-R}(y_l, p_l)$ as $u(f), f \in \mathcal{F}$. Denote the dual variables corresponding to the second group of constraints in $\text{OPT}(y_l, p_l)$ and $\text{OPT-R}(y_l, p_l)$ as $v_i(f), f \in \mathcal{F}, i \in \mathcal{N}, i \neq s(f), d(f)$. Denote the dual variables corresponding to the third group of constraints in $\text{OPT}(y_l, p_l)$ and $\text{OPT-R}(y_l, p_l)$ as $q_l, l \in \mathcal{L}$. Then, $\text{D}(y_l, p_l)$ can be written as

$$\begin{aligned} \text{D}(y_l, p_l): \quad & \min \sum_{l \in \mathcal{L}} \bar{c}_l q_l \\ & \text{s.t. } -u(f) \geq w(f) \quad (f \in \mathcal{F}) \end{aligned} \tag{17}$$

$$v_i(f) + q_l \geq 0 \quad (f \in \mathcal{F}, l \in \mathcal{L}^{\text{Out}}(i), i \neq s(f), d(f))$$

$$-v_i(f) + q_l \geq 0 \quad (f \in \mathcal{F}, l \in \mathcal{L}^{\text{In}}(i), i \neq s(f), d(f))$$

$$u(f) + q_l \geq 0 \quad (f \in \mathcal{F}, l \in \mathcal{L}^{\text{Out}}(s(f))) \tag{18}$$

$$u(f), v_i(f) \text{ unrestricted, } q_l \geq 0.$$

Dual problem $\text{D-R}(y_l, p_l)$ can be written as

$$\begin{aligned} \text{D-R}(y_l, p_l): \quad & \min \sum_{l \in \mathcal{L}} c_l^\dagger q_l \\ & \text{s.t. All constraints in } \text{D}(y_l, p_l). \end{aligned}$$

Combining (17) and (18) gives us $q_l \geq w(f), l \in \mathcal{L}^{\text{Out}}(s(f)), f \in \mathcal{F}$. Since these two dual problems are both minimization problems, it is easy to see that the solution with $q_l^* = w(f), (l \in \mathcal{L}^{\text{Out}}(s(f)), f \in \mathcal{F})$ and all the other variables equal to zero is the optimal solution to both $\text{D}(y_l, p_l)$ and $\text{D-R}(y_l, p_l)$. That is

$$q_l^* = \begin{cases} w(f) & \text{if link } l \text{ is an outgoing link from } s(f); \\ 0 & \text{otherwise.} \end{cases} \tag{19}$$

Then, we have

$$\bar{z} - z^\dagger = \sum_{l \in \mathcal{L}} \bar{c}_l q_l^* - \sum_{l \in \mathcal{L}} c_l^\dagger q_l^* = \sum_{l \in \mathcal{L}} (\bar{c}_l - c_l^\dagger) q_l^* = \sum_{f \in \mathcal{F}} \sum_{l \in \mathcal{L}^{\text{Out}}(s(f))} (\bar{c}_l - c_l^\dagger) w(f), \quad (20)$$

where the first equality holds due to the strong duality property [1, Chapter 6] and the third equality holds due to (19). Note that the gap between \bar{c}_l and c_l^\dagger is

$$\bar{c}_l - c_l^\dagger \leq \frac{B_l}{\ln 2} \epsilon, \quad (21)$$

since the maximum error of our linear approximation is ϵ . Combining (20) and (21) gives us

$$\bar{z} - z^\dagger \leq \epsilon \cdot \sum_{f \in \mathcal{F}} \sum_{l \in \mathcal{L}^{\text{Out}}(s(f))} \frac{B_l}{\ln 2} w(f).$$

This completes the proof. \square

Now we are ready to characterize the performance gap between the optimal objective values of OPT-R and OPT as follows.

Theorem 1 *The gap between the optimal objective values of OPT and OPT-R is no more than*

$$\epsilon \cdot \sum_{f \in \mathcal{F}} \sum_{l \in \mathcal{L}_s^{\text{Out}}(f)} \frac{B_l}{\ln 2} w(f).$$

Proof Denote \mathbf{x}^* and z^* the optimal solution and the optimal objective value of OPT, respectively. From Lemma 4, since \mathbf{x}^* is a particular case of $\bar{\mathbf{x}}$, we know that there exists a feasible solution of OPT-R \mathbf{x}_R corresponding to \mathbf{x}^* such that the performance gap between \mathbf{x}^* and \mathbf{x}_R is at most $\epsilon \cdot \sum_{f \in \mathcal{F}} \sum_{l \in \mathcal{L}_s^{\text{Out}}(f)} \frac{B_l}{\ln 2} w(f)$. Denote z_R the objective value of solution \mathbf{x}_R to OPT-R. Then, we have

$$z^* - z_R \leq \epsilon \cdot \sum_{f \in \mathcal{F}} \sum_{l \in \mathcal{L}_s^{\text{Out}}(f)} \frac{B_l}{\ln 2} w(f). \quad (22)$$

Denote z_R^* the optimal objective value of OPT-R. Since z_R is the objective value of a feasible solution to OPT-R while z_R^* is the optimal objective value of OPT-R, we have

$$z_R^* \geq z_R. \quad (23)$$

Combining (22) and (23), we have $z^* - z_R^* \leq \epsilon \cdot \sum_{f \in \mathcal{F}} \sum_{l \in \mathcal{L}_s^{\text{Out}}(f)} \frac{B_l}{\ln 2} w(f)$.

Based on Theorem 1, we are able to give an algorithm to obtain a near-optimal solution to OPT with performance guarantee as follows.

Algorithm 2 Input: *Given a desired performance gap γ for the solution.*

1. Compute ϵ based on

$$\epsilon \cdot \sum_{f \in \mathcal{F}} \sum_{l \in \mathcal{L}_{s(f)}^{\text{Out}}} \frac{B_l}{\ln 2} w(f) = \gamma. \quad (24)$$

2. Compute $m_l^{(k)}$ and $s_l^{(k)}$ by Algorithm 1.

3. Construct OPT-R based on $m_l^{(k)}$ and $s_l^{(k)}$.

4. Solve OPT-R optimally with CPLEX.

Upon the completion of Algorithm 2, we will have a near-optimal solution to OPT with a guaranteed performance bound (no more than γ from the optimal objective value).

4 Maximizing Throughput and Minimizing Network-wide Energy Consumption

In the previous section, we have shown how to maximize network throughput while satisfying a given total network-wide energy budget. The problem was formulated as a *single objective* optimization problem OPT. In this section, we take one step further. We are interested in maximizing network throughput while minimizing energy consumption. We cast this problem into a *multicriteria* optimization problem with two objectives. Mathematically, this problem can be written as follows:

$$\begin{aligned} \mathbf{MP:} \quad & \max \sum_{f \in \mathcal{F}} w(f)r(f) \\ & \min \sum_{l \in \mathcal{L}} (p_l + y_l P_d) \\ & \text{s.t.} \quad \text{Constraints (1), (2), (3), (4), (8)} \\ & \quad \text{Variables } y_l \in \{0, 1\}, p_l, r_l(f), r(f) \geq 0 \ (l \in \mathcal{L}, f \in \mathcal{F}). \end{aligned}$$

As we can see, minimizing network-wide energy consumption and maximizing network throughput are two conflicting objectives. For such a problem, it is in general not possible to find a single

feasible solution that is optimal for both objectives at the same time. For example, when P is minimized (i.e., 0), U is also 0 but is not maximized. Therefore, it is important to clarify what we mean by optimal solutions.

In this paper, we are interested in finding the so-called weakly Pareto-optimal solutions [5]. Weakly Pareto-optimal solutions are optimal in the sense that it is impossible to improve the performance of both objectives simultaneously. Specifically, we say that (P^*, U^*) is a weakly Pareto-optimal point to problem MP if there does not exist another solution to problem MP with (P, U) such that $P < P^*$ and $U > U^*$.

To find weakly Pareto-optimal points, we transform the multicriteria optimization problem into a single objective optimization problem. This can be done by moving the second objective (i.e., $\sum_{l \in \mathcal{L}} (p_l + y_l P_d)$) into the constraints as follows.

$$\begin{aligned}
 \mathbf{SP}(P_{\text{net}}): \quad & \max \quad \sum_{f \in \mathcal{F}} w(f)r(f) \\
 \text{s.t.} \quad & \sum_{l \in \mathcal{L}} (p_l + y_l P_d) \leq P_{\text{net}} \\
 & \text{Constraints(1), (2), (3), (4), (8)} \\
 & \text{Variables } y_l \in \{0, 1\}, p_l, r_l(f), r(f) \geq 0 \ (l \in \mathcal{L}, f \in \mathcal{F}).
 \end{aligned}$$

We see that this single objective optimization problem is precisely the same as OPT that we studied earlier. For a fixed value of P_{net} , solving $\mathbf{SP}(P_{\text{net}})$ will give us *one* weakly Pareto-optimal point of problem MP [5]. By varying P_{net} from 0 to $P_{\text{net}}^{\max} = |\mathcal{L}| \cdot (P_{\max} + P_d)$, we can obtain all the weakly Pareto-optimal points. These points provide a mapping from the network-wide energy budget P_{net} to the maximum network throughput U , which we denote as $\pi : P_{\text{net}} \rightarrow U$. This mapping $U = \pi(P_{\text{net}})$ is an optimal throughput-energy curve, which characterizes how the maximum network throughput changes as the total network-wide energy consumption rate varies. This curve is useful for network operators to have a holistic view of the entire optimal trade-off curve and decide which point to choose so as to meet their needs.

We have several interesting properties about this optimal throughput-energy curve $U = \pi(P_{\text{net}})$, which are shown in Property 1.

Property 1 *The optimal throughput-energy curve $U = \pi(P_{\text{net}})$ has the following properties.*

1. $\pi(P_{\text{net}})$ is a nondecreasing function of P_{net} .
2. $\pi(P_{\text{net}})$ has a starting point $(P_{\text{start}}, 0)$, i.e., $\pi(P_{\text{net}}) = 0$ for $P_{\text{net}} \leq P_{\text{start}}$ and $\pi(P_{\text{net}}) > 0$ for $P_{\text{net}} > P_{\text{start}}$.
3. $\pi(P_{\text{net}})$ has a saturation point $(P_{\text{sat}}, U_{\text{sat}})$, i.e., $\pi(P_{\text{net}}) = U_{\text{sat}}$ for $P_{\text{net}} \geq P_{\text{sat}}$ and $\pi(P_{\text{net}}) < U_{\text{sat}}$ for $P_{\text{net}} < P_{\text{sat}}$.

Proof We prove each property as follows.

1. Assume $P_{\text{net}}^{(1)} < P_{\text{net}}^{(2)}$. We need to show that $U(P_{\text{net}}^{(1)}) \leq U(P_{\text{net}}^{(2)})$. Note that $U(P_{\text{net}}^{(1)})$ and $U(P_{\text{net}}^{(2)})$ are the optimal objectives of $\text{SP}(P_{\text{net}}^{(1)})$ and $\text{SP}(P_{\text{net}}^{(2)})$, respectively. Since $P_{\text{net}}^{(1)} < P_{\text{net}}^{(2)}$, the feasible region of $\text{SP}(P_{\text{net}}^{(1)})$ falls inside the feasible region of $\text{SP}(P_{\text{net}}^{(2)})$. Thus, we have $U(P_{\text{net}}^{(1)}) \leq U(P_{\text{net}}^{(2)})$.
2. Such starting point exists because when a link is active, it must consume a constant power P_d . For a session to have positive throughput, it must activate all the links along the path that are used by this session for transporting data. Thus, P_{start} can be determined by the session that uses the minimum number of hops from its source to its destination. Denote m_f the minimum hops of session f . Then, P_{start} can be written as $P_{\text{start}} = P_d \cdot \min\{m_f : f \in \mathcal{F}\}$.
3. The saturation point $(P_{\text{sat}}, U_{\text{sat}})$ can be determined as follows. We can first compute the maximum network throughput without network-wide energy constraint, i.e., solving the following optimization problem.

$$\begin{aligned} \max \quad & \sum_{f \in \mathcal{F}} w(f)r(f) \\ \text{s.t.} \quad & \text{Constraints (1), (2), (3), (4), (8)}. \end{aligned}$$

The optimal objective value of the above problem is U_{sat} . Then, we determine the minimum

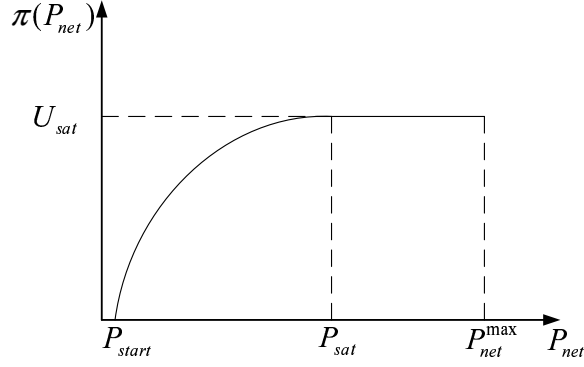


Figure 4: An illustration of optimal throughput-energy curve.

energy that can achieves this throughput by solving the following optimization problem.

$$\begin{aligned} \min \quad & \sum_{l \in \mathcal{L}} (p_l + y_l P_c) \\ \text{s.t.} \quad & w(f)r(f) = U_{\text{sat}} \end{aligned}$$

Constraints (1), (2), (3), (4), (8).

Based on Property 1, Fig. 4 illustrates a typical optimal throughput-energy curve for a multi-hop wireless network.

5 Numerical Results

In this section, we present some numerical results to illustrate our theoretical findings in Section 3 and 4.

5.1 Simulation Settings

We consider a 50-node network deployed in a 1000×1000 square area and a 100-node network deployed in a 1500×1500 square area. The topologies of the 50-node network and 100-node network are shown in Fig. 5 and Fig. 6, respectively. We assume that all units are normalized with appropriate dimensions. We assume the maximum transmission range is 200 and the maximum transmission power is $P_{\text{max}} = 2$. We assume node device power consumption is $P_d = 0.2$. The

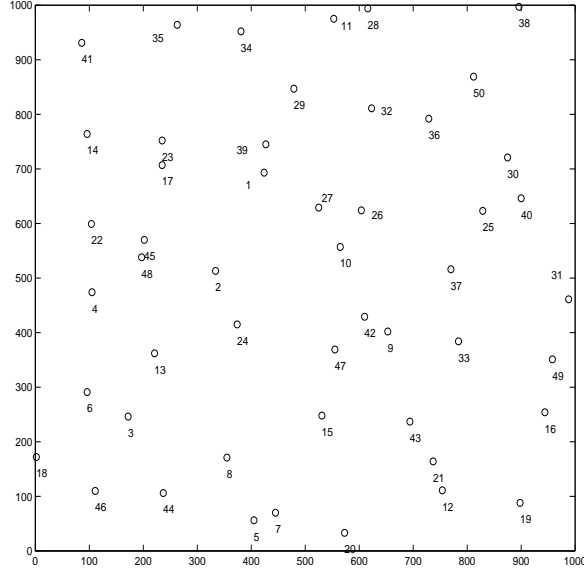


Figure 5: The topology for a 50-node network.

Table 2: Each session's source node, destination node, and weight for the 50-node network.

Session f	Source node $s(f)$	Dest. node $d(f)$	Weight $w(f)$
1	10	35	0.5
2	35	21	0.9
3	5	23	0.7
4	43	14	0.6
5	29	7	0.8

channel bandwidth is $B_l = 1$ for all links and channel gain is $h_l = d_l^{-4}$, where d_l is the distance between link l 's transmitting node and receiving node.

5.2 Results for the 50-node Network

Within this network, we assume there are $|\mathcal{F}| = 5$ user sessions, with source node and destination node of each session chosen randomly. Table 2 lists the source node, destination node, and weight for each session in the network.

5.2.1 Near-Optimal Solution for OPT

In this case study, we assume the maximum network-wide energy consumption rate $P_{\text{net}} = 40$. We set the maximum acceptable performance gap between the optimal objectives of OPT and

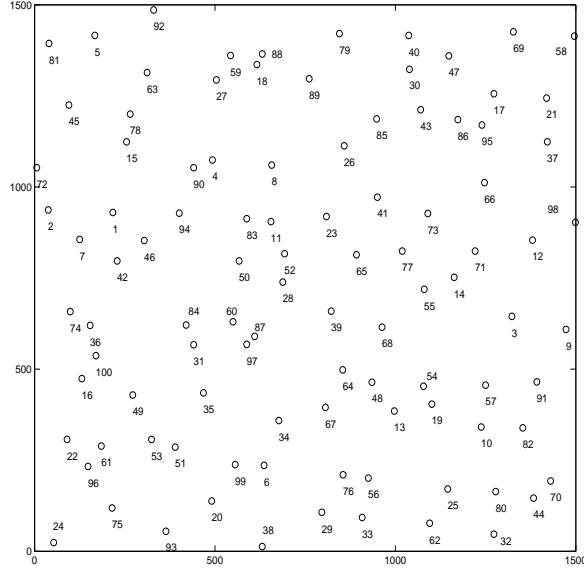


Figure 6: The topology for a 100-node network.

linear approximation OPT-R as $\gamma = 0.1$. We apply Algorithm 2 here. Based on (24), we compute

$$\epsilon = \frac{\gamma \cdot \ln 2}{\sum_{f \in \mathcal{F}} \sum_{l \in \mathcal{L}_s^{\text{Out}}(f)} \frac{B_l}{\ln 2} w(f)} = 0.0046. \text{ Based on } \epsilon, \text{ we compute the piece-wise linear approximation}$$

according to Algorithm 1.

Then we can use CPLEX to solve OPT-R. We obtain that the maximum network throughput is $U = 22.12$. The achieved session data rates are $r_1 = 4.41$, $r_2 = 6.39$, $r_3 = 9.37$, $r_4 = 3.89$, and $r_5 = 6.62$. Our algorithm gives power control and flow routing solutions for the network. We list the power assignment for each active link in Table 3, and the flow routing results in Table 4.

5.2.2 The Optimal Throughput-Energy Curve

For the same 50-node network instance, we characterize its optimal throughput-energy curve based on our theoretical results in Section 4. We show the optimal throughput-energy curve in Fig. 7. From the figure, we can see all three properties as stated in Property 1. As shown in the figure, the curve is nondecreasing. The network throughput keeps at zero when the network energy consumption rate is no greater than P_{start} . For the starting point $(P_{\text{start}}, 0)$, since session 1 needs at least 5 hops, we have $P_{\text{start}} = 5 \cdot P_d = 1$. For the saturation point $(P_{\text{sat}}, U_{\text{sat}})$, we get $(P_{\text{sat}}, U_{\text{sat}}) = (106.20, 36.14)$. The network throughput stops increasing and keeps as 36.14 when

Table 3: Power assignment on each active link in the final solution for the 50-node network.

Link	Power	Link	Power	Link	Power
1 → 27	0.1819	1 → 23	0.4317	1 → 17	0.4658
2 → 45	0.1958	2 → 24	0.0370	3 → 44	0.2050
3 → 13	0.1805	3 → 6	0.0350	4 → 45	0.2083
4 → 22	0.1692	4 → 13	0.2441	5 → 44	0.2652
5 → 8	0.1775	5 → 7	0.0313	6 → 4	0.6487
7 → 15	0.4290	7 → 8	0.1534	8 → 44	0.0707
8 → 15	0.2924	8 → 7	0.1209	8 → 3	0.5524
9 → 43	0.1794	9 → 10	0.2835	10 → 47	0.5756
10 → 42	0.0952	10 → 27	0.3033	10 → 26	0.0101
10 → 9	0.2166	10 → 1	0.2355	11 → 34	0.2547
11 → 32	0.1617	13 → 4	0.4853	13 → 3	0.0908
14 → 22	0.2196	15 → 47	0.2544	15 → 8	0.4918
15 → 7	0.5515	17 → 45	0.1424	17 → 23	0.0151
17 → 14	0.1431	22 → 45	0.0628	22 → 17	0.3000
22 → 14	0.2092	24 → 47	0.3587	24 → 2	0.0575
25 → 37	0.1283	26 → 32	0.3506	27 → 39	0.4733
27 → 10	0.3033	27 → 1	0.1177	29 → 39	0.5181
29 → 34	0.1950	29 → 32	0.0776	29 → 1	0.6365
30 → 25	0.0791	32 → 36	0.0774	32 → 11	0.2840
33 → 43	0.5081	34 → 35	0.4009	34 → 29	0.3055
34 → 11	0.1450	35 → 41	0.3099	35 → 34	0.4009
36 → 30	0.3999	37 → 33	0.1787	39 → 29	0.0787
39 → 27	0.3061	39 → 23	0.1054	39 → 17	0.5299
41 → 14	0.2310	42 → 15	0.4273	42 → 10	0.2433
43 → 47	0.3793	43 → 21	0.4274	43 → 9	0.2347
44 → 5	0.3408	44 → 3	0.6235	45 → 23	0.1872
45 → 22	0.0306	45 → 17	0.2270	45 → 4	0.1253
45 → 2	0.1260	47 → 43	0.3982	47 → 42	0.0315
47 → 24	0.5573	47 → 15	0.1061		

Table 4: Flow routing results for the 50-node network.

Session f	Flow rate on each link attributed to session f
1	$r_{10 \rightarrow 27}(1) = 2.48, r_{10 \rightarrow 26}(1) = 1.93, r_{11 \rightarrow 34}(1) = 1.93$ $r_{26 \rightarrow 32}(1) = 1.93, r_{27 \rightarrow 39}(1) = 2.48, r_{29 \rightarrow 34}(1) = 2.48$ $r_{32 \rightarrow 11}(1) = 1.93, r_{34 \rightarrow 35}(1) = 4.41, r_{39 \rightarrow 29}(1) = 2.48$
2	$r_{1 \rightarrow 27}(2) = 1.65, r_{2 \rightarrow 24}(2) = 1.98, r_{9 \rightarrow 43}(2) = 1.65$ $r_{10 \rightarrow 9}(2) = 1.65, r_{11 \rightarrow 32}(2) = 1.38, r_{14 \rightarrow 22}(2) = 1.98$ $r_{22 \rightarrow 45}(2) = 1.98, r_{24 \rightarrow 47}(2) = 1.98, r_{25 \rightarrow 37}(2) = 2.76$ $r_{27 \rightarrow 10}(2) = 1.65, r_{29 \rightarrow 32}(2) = 1.38, r_{29 \rightarrow 1}(2) = 1.65,$ $r_{30 \rightarrow 25}(2) = 2.76, r_{32 \rightarrow 36}(2) = 2.76, r_{33 \rightarrow 43}(2) = 2.76$ $r_{34 \rightarrow 29}(2) = 3.03, r_{34 \rightarrow 11}(2) = 1.38, r_{35 \rightarrow 41}(2) = 1.98$ $r_{35 \rightarrow 34}(2) = 4.41, r_{36 \rightarrow 30}(2) = 2.76, r_{37 \rightarrow 33}(2) = 2.76$ $r_{41 \rightarrow 14}(2) = 1.98, r_{43 \rightarrow 21}(2) = 6.39, r_{45 \rightarrow 2}(2) = 1.98$ $r_{47 \rightarrow 43}(2) = 1.98$
3	$r_{1 \rightarrow 23}(3) = 1.93, r_{1 \rightarrow 17}(3) = 0.28, r_{2 \rightarrow 45}(3) = 0.55$ $r_{3 \rightarrow 13}(3) = 3.03, r_{3 \rightarrow 6}(3) = 2.76, r_{4 \rightarrow 45}(3) = 2.80$ $r_{4 \rightarrow 22}(3) = 2.98, r_{5 \rightarrow 44}(3) = 1.93, r_{5 \rightarrow 8}(3) = 3.03$ $r_{5 \rightarrow 7}(3) = 4.41, r_{6 \rightarrow 4}(3) = 2.76, r_{7 \rightarrow 15}(3) = 1.93$ $r_{7 \rightarrow 8}(3) = 2.48, r_{8 \rightarrow 44}(3) = 1.65, r_{8 \rightarrow 15}(3) = 1.65$ $r_{8 \rightarrow 3}(3) = 2.21, r_{10 \rightarrow 27}(3) = 1.65, r_{10 \rightarrow 1}(3) = 1.38$ $r_{13 \rightarrow 4}(3) = 3.03, r_{15 \rightarrow 47}(3) = 3.58, r_{17 \rightarrow 23}(3) = 5.24$ $r_{22 \rightarrow 45}(3) = 0.78, r_{22 \rightarrow 17}(3) = 2.21, r_{24 \rightarrow 2}(3) = 0.55$ $r_{27 \rightarrow 39}(3) = 0.83, r_{27 \rightarrow 1}(3) = 0.83, r_{39 \rightarrow 23}(3) = 0.83$ $r_{42 \rightarrow 10}(3) = 3.03, r_{44 \rightarrow 3}(3) = 3.58, r_{45 \rightarrow 23}(3) = 1.38$ $r_{45 \rightarrow 17}(3) = 2.76, r_{47 \rightarrow 42}(3) = 3.03, r_{47 \rightarrow 24}(3) = 0.55$
4	$r_{1 \rightarrow 17}(4) = 1.93, r_{2 \rightarrow 45}(4) = 1.93, r_{9 \rightarrow 10}(4) = 1.93$ $r_{10 \rightarrow 27}(4) = 1.93, r_{17 \rightarrow 14}(4) = 1.93, r_{22 \rightarrow 14}(4) = 1.93$ $r_{24 \rightarrow 2}(4) = 1.93, r_{27 \rightarrow 1}(4) = 1.93, r_{43 \rightarrow 47}(4) = 1.93$ $r_{43 \rightarrow 9}(4) = 1.93, r_{45 \rightarrow 22}(4) = 1.93, r_{47 \rightarrow 24}(4) = 1.93$
5	$r_{1 \rightarrow 27}(5) = 1.65, r_{3 \rightarrow 44}(5) = 2.21, r_{4 \rightarrow 13}(5) = 2.21$ $r_{5 \rightarrow 7}(5) = 2.21, r_{8 \rightarrow 7}(5) = 2.21, r_{10 \rightarrow 47}(5) = 2.48$ $r_{10 \rightarrow 42}(5) = 1.93, r_{13 \rightarrow 3}(5) = 2.21, r_{15 \rightarrow 8}(5) = 2.21$ $r_{15 \rightarrow 7}(5) = 2.21, r_{17 \rightarrow 45}(5) = 2.21, r_{27 \rightarrow 10}(5) = 4.41$ $r_{29 \rightarrow 39}(5) = 4.96, r_{29 \rightarrow 1}(5) = 1.65, r_{39 \rightarrow 27}(5) = 2.76$ $r_{39 \rightarrow 17}(5) = 2.21, r_{42 \rightarrow 15}(5) = 1.93, r_{44 \rightarrow 5}(5) = 2.21$ $r_{45 \rightarrow 4}(5) = 2.21, r_{47 \rightarrow 15}(5) = 2.48$

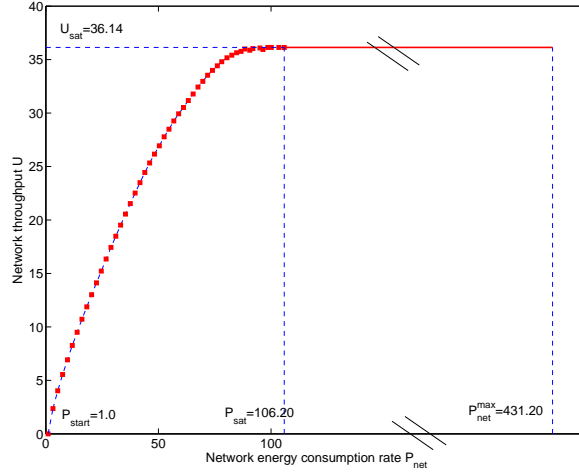


Figure 7: The optimal throughput-energy curve for the 50-node network, where the “\\” sign in the figure indicates nonlinear scale for $P_{\text{net}} \in [106.20, 431.20]$.

the network energy consumption rate exceeds $P_{\text{sat}} = 106.20$.

5.3 Results for the 100-node Network

For the 100-node network, we assume that there are $|\mathcal{F}| = 10$ active sessions in the network, with each session’s source node, destination node, and weight given in Table 5.

We assume that maximum network-wide energy consumption rate $P_{\text{net}} = 100$. By employing our method, we obtain that the maximum network throughput is $U = 42.00$. The achieved session data rates are $r_1 = 10.86$, $r_2 = 1.63$, $r_3 = 7.09$, $r_4 = 4.03$, $r_5 = 9.71$, $r_6 = 4.00$, $r_7 = 9.90$, $r_8 = 4.91$, and $r_9 = 8.08$, and $r_{10} = 7.19$. The detailed results for power assignment and flow routing are given in Table 6 Table 7. The optimal throughput-energy curve for the 100-node network is shown in Fig. 8.

6 Conclusion

Network-wide energy consumption has become an important concern for network operators. In this paper, we studied two tightly coupled problems for network-wide energy conservation. In the first problem, we studied how to maximize network throughput under a network-wide energy constraint. We formulated this problem into a mixed-integer nonlinear program (MINLP) and

Table 5: Each session's source node, destination node, and weight for the 100-node network.

Session f	Source node $s(f)$	Dest. node $d(f)$	Weight $w(f)$
1	40	26	0.9
2	27	17	0.8
3	4	55	0.7
4	31	41	0.6
5	78	100	0.8
6	7	83	0.6
7	73	91	0.3
8	12	10	0.4
9	64	38	0.6
10	51	56	0.5

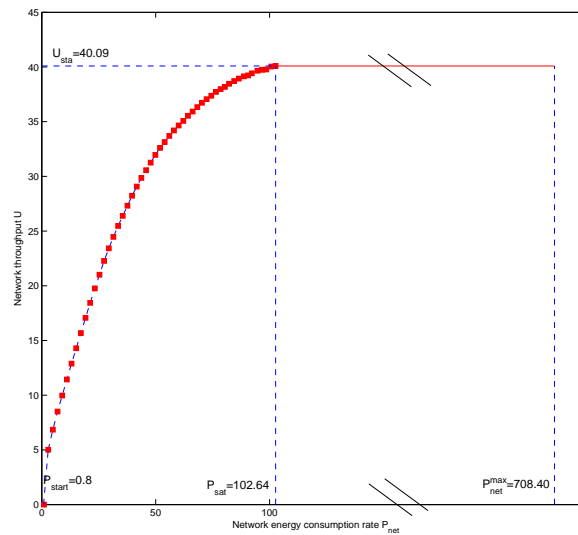


Figure 8: The optimal throughput-energy curve for the 100-node network, where the “\” sign in the figure indicates nonlinear scale for $P_{net} \in [102.64, 708.40]$.

proposed a near-optimal solution with guaranteed performance bound. In the second problem, we explored joint optimization of both network throughput and energy consumption via a multicriteria optimization framework. We showed that the weakly Pareto-optimal points in the solution can characterize an optimal throughput-energy curve. The results in this paper offer both solutions and insights to network operators when total energy consumption for the entire network is of greater concern than local energy consumption.

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Table 6: Power assignment on each active link in the final solution for the 100-node network.

Link	Power	Link	Power	Link	Power
1 → 46	0.1610	34 → 67	1.5375	65 → 41	0.3069
1 → 42	0.2142	34 → 6	0.4389	65 → 39	1.0259
2 → 7	0.2847	35 → 84	0.2735	66 → 73	0.5698
3 → 91	0.3482	36 → 100	0.3999	66 → 71	0.2038
3 → 9	0.1693	39 → 68	0.6296	67 → 76	1.3448
4 → 83	0.9835	39 → 64	0.9111	67 → 48	0.0920
4 → 8	1.0165	40 → 47	1.0196	67 → 34	0.4997
6 → 99	0.0637	40 → 30	0.9804	67 → 13	0.0635
6 → 34	0.3062	41 → 77	0.2932	68 → 64	0.2041
7 → 74	1.7122	41 → 26	1.2846	68 → 54	1.0492
7 → 46	0.1229	41 → 23	0.1969	68 → 48	0.7467
7 → 1	0.1649	42 → 74	1.0565	71 → 55	0.6433
8 → 83	0.1445	42 → 36	0.9435	71 → 14	0.2603
8 → 11	0.2208	43 → 86	0.0492	72 → 2	0.2990
9 → 91	0.2227	43 → 85	0.3158	73 → 77	0.5455
10 → 80	0.3385	45 → 72	2.0000	73 → 71	0.2047
10 → 25	0.4205	46 → 94	0.3406	73 → 41	0.8028
11 → 52	0.0571	46 → 42	0.0634	73 → 14	0.4035
11 → 23	0.9333	47 → 86	0.2463	74 → 100	0.3717
12 → 71	2.0000	47 → 43	0.2360	74 → 36	0.0181
13 → 56	1.8806	47 → 17	0.1470	76 → 56	0.0249
13 → 54	0.0581	48 → 54	0.6765	77 → 65	0.3229
13 → 19	0.0613	48 → 19	0.6538	77 → 55	0.6875
14 → 77	0.1055	48 → 13	0.3289	77 → 41	0.2516
14 → 55	0.1035	50 → 52	0.0788	77 → 14	0.2097
14 → 3	1.7910	51 → 99	0.8556	78 → 45	1.2430
15 → 90	0.9260	51 → 35	0.1607	78 → 15	0.1874
15 → 1	1.0740	51 → 20	0.3715	79 → 40	0.2861
18 → 89	0.1069	52 → 65	1.2163	80 → 25	0.0982
19 → 57	0.9917	52 → 28	0.0143	82 → 91	0.1406
19 → 10	1.0083	52 → 23	0.7694	83 → 11	0.0557
20 → 99	0.0729	54 → 57	1.0144	84 → 87	0.2759
20 → 38	1.9271	54 → 19	0.0057	85 → 26	2.0000
23 → 65	0.4337	54 → 10	0.9799	86 → 95	0.0103
23 → 52	0.2177	55 → 68	1.8836	86 → 66	0.2518
23 → 41	0.8404	57 → 91	0.4561	87 → 28	0.1607
25 → 62	0.1981	57 → 82	0.2743	89 → 79	0.1058
27 → 18	0.0430	57 → 10	0.0381	90 → 94	0.1749
28 → 52	0.0117	60 → 50	0.2361	94 → 83	1.8668
28 → 39	0.8018	60 → 28	0.2986	94 → 46	0.1332
29 → 38	2.0000	62 → 33	1.9127	95 → 66	0.2907
30 → 85	0.4852	64 → 67	0.2590	99 → 34	0.2677
30 → 43	0.2821	64 → 48	0.5956	99 → 20	0.3143
31 → 60	0.3863	64 → 13	0.8886	99 → 6	0.0444
33 → 29	0.2502	65 → 77	0.6673		

Table 7: Flow routing results for the 100-node network.

Session f	Flow rate on each link attributed to session f
1	$r_{14 \rightarrow 77}(1) = 1.36, r_{30 \rightarrow 85}(1) = 2.96, r_{30 \rightarrow 43}(1) = 4.09, r_{40 \rightarrow 47}(1) = 3.82, r_{40 \rightarrow 30}(1) = 7.04, r_{41 \rightarrow 26}(1) = 4.09$ $r_{43 \rightarrow 86}(1) = 2.27, r_{43 \rightarrow 85}(1) = 3.82, r_{47 \rightarrow 86}(1) = 1.82, r_{47 \rightarrow 43}(1) = 2.00, r_{66 \rightarrow 73}(1) = 2.72, r_{66 \rightarrow 71}(1) = 1.36$ $r_{71 \rightarrow 14}(1) = 1.36, r_{73 \rightarrow 41}(1) = 2.72, r_{77 \rightarrow 41}(1) = 1.36, r_{85 \rightarrow 26}(1) = 6.77, r_{86 \rightarrow 95}(1) = 2.50, r_{86 \rightarrow 66}(1) = 1.59$ $r_{95 \rightarrow 66}(1) = 2.50$
2	$r_{18 \rightarrow 89}(2) = 1.63, r_{27 \rightarrow 18}(2) = 1.63, r_{40 \rightarrow 47}(2) = 1.63, r_{47 \rightarrow 17}(2) = 1.63, r_{79 \rightarrow 40}(2) = 1.63, r_{89 \rightarrow 79}(2) = 1.63$
3	$r_{4 \rightarrow 83}(3) = 3.18, r_{4 \rightarrow 8}(3) = 3.89, r_{8 \rightarrow 83}(3) = 1.62, r_{8 \rightarrow 11}(3) = 2.27, r_{11 \rightarrow 52}(3) = 2.96, r_{11 \rightarrow 23}(3) = 4.11$ $r_{14 \rightarrow 55}(3) = 2.04, r_{23 \rightarrow 65}(3) = 3.86, r_{23 \rightarrow 41}(3) = 2.35, r_{41 \rightarrow 77}(3) = 2.35, r_{52 \rightarrow 65}(3) = 0.86, r_{52 \rightarrow 23}(3) = 2.10$ $r_{65 \rightarrow 77}(3) = 4.72, r_{77 \rightarrow 55}(3) = 5.03, r_{77 \rightarrow 14}(3) = 2.04, r_{83 \rightarrow 11}(3) = 4.80$
4	$r_{23 \rightarrow 41}(4) = 1.76, r_{28 \rightarrow 52}(4) = 2.04, r_{31 \rightarrow 60}(4) = 4.03, r_{50 \rightarrow 52}(4) = 1.99, r_{52 \rightarrow 65}(4) = 2.27, r_{52 \rightarrow 23}(4) = 1.76$ $r_{60 \rightarrow 50}(4) = 1.99, r_{60 \rightarrow 28}(4) = 2.04, r_{65 \rightarrow 41}(4) = 2.27$
5	$r_{1 \rightarrow 46}(5) = 0.05, r_{1 \rightarrow 42}(5) = 2.95, r_{2 \rightarrow 7}(5) = 3.93, r_{7 \rightarrow 74}(5) = 3.55, r_{7 \rightarrow 46}(5) = 0.38, r_{15 \rightarrow 90}(5) = 2.78$ $r_{15 \rightarrow 1}(5) = 3.00, r_{36 \rightarrow 100}(5) = 6.31, r_{42 \rightarrow 74}(5) = 3.18, r_{42 \rightarrow 36}(5) = 2.98, r_{45 \rightarrow 72}(5) = 3.93, r_{46 \rightarrow 42}(5) = 3.21$ $r_{72 \rightarrow 2}(5) = 3.93, r_{74 \rightarrow 100}(5) = 3.41, r_{74 \rightarrow 36}(5) = 3.33, r_{78 \rightarrow 45}(5) = 3.93, r_{78 \rightarrow 15}(5) = 5.78, r_{90 \rightarrow 94}(5) = 2.78$ $r_{94 \rightarrow 46}(5) = 2.78$
6	$r_{1 \rightarrow 46}(6) = 3.24, r_{7 \rightarrow 46}(6) = 0.76, r_{7 \rightarrow 1}(6) = 3.24, r_{46 \rightarrow 94}(6) = 4.00, r_{94 \rightarrow 83}(6) = 4.00$
7	$r_{3 \rightarrow 91}(7) = 1.82, r_{3 \rightarrow 9}(7) = 1.99, r_{9 \rightarrow 91}(7) = 1.99, r_{14 \rightarrow 3}(7) = 3.81, r_{19 \rightarrow 57}(7) = 2.95, r_{23 \rightarrow 52}(7) = 2.27$ $r_{28 \rightarrow 39}(7) = 2.27, r_{39 \rightarrow 68}(7) = 2.81, r_{39 \rightarrow 64}(7) = 3.19, r_{41 \rightarrow 23}(7) = 2.27, r_{48 \rightarrow 54}(7) = 3.14, r_{48 \rightarrow 19}(7) = 2.95$ $r_{52 \rightarrow 28}(7) = 2.27, r_{54 \rightarrow 57}(7) = 3.14, r_{55 \rightarrow 68}(7) = 0.10, r_{57 \rightarrow 91}(7) = 3.60, r_{57 \rightarrow 82}(7) = 2.50, r_{64 \rightarrow 48}(7) = 3.19$ $r_{65 \rightarrow 39}(7) = 3.72, r_{68 \rightarrow 48}(7) = 2.91, r_{71 \rightarrow 55}(7) = 0.10, r_{71 \rightarrow 14}(7) = 1.77, r_{73 \rightarrow 77}(7) = 4.54, r_{73 \rightarrow 71}(7) = 1.87$ $r_{73 \rightarrow 41}(7) = 1.45, r_{73 \rightarrow 14}(7) = 2.04, r_{77 \rightarrow 65}(7) = 3.72, r_{77 \rightarrow 41}(7) = 0.82, r_{82 \rightarrow 91}(7) = 2.50$
8	$r_{12 \rightarrow 71}(8) = 4.92, r_{13 \rightarrow 54}(8) = 1.02, r_{14 \rightarrow 55}(8) = 2.06, r_{19 \rightarrow 57}(8) = 1.14, r_{19 \rightarrow 10}(8) = 1.80, r_{48 \rightarrow 54}(8) = 0.94$ $r_{54 \rightarrow 57}(8) = 0.51, r_{54 \rightarrow 19}(8) = 2.93, r_{54 \rightarrow 10}(8) = 1.48, r_{55 \rightarrow 68}(8) = 4.92, r_{57 \rightarrow 10}(8) = 1.64$ $r_{64 \rightarrow 13}(8) = 1.02, r_{68 \rightarrow 64}(8) = 1.02, r_{68 \rightarrow 54}(8) = 2.95, r_{68 \rightarrow 48}(8) = 0.94, r_{71 \rightarrow 55}(8) = 2.85, r_{71 \rightarrow 14}(8) = 2.06$
9	$r_{6 \rightarrow 99}(9) = 4.04, r_{10 \rightarrow 80}(9) = 2.04, r_{10 \rightarrow 25}(9) = 1.99, r_{13 \rightarrow 54}(9) = 1.48, r_{13 \rightarrow 19}(9) = 2.56, r_{19 \rightarrow 10}(9) = 2.56$ $r_{20 \rightarrow 38}(9) = 4.04, r_{25 \rightarrow 62}(9) = 4.03, r_{29 \rightarrow 38}(9) = 4.03, r_{33 \rightarrow 29}(9) = 4.03, r_{34 \rightarrow 6}(9) = 4.04, r_{48 \rightarrow 13}(9) = 3.47$ $r_{54 \rightarrow 10}(9) = 1.48, r_{62 \rightarrow 33}(9) = 4.03, r_{64 \rightarrow 67}(9) = 4.04, r_{64 \rightarrow 48}(9) = 3.47, r_{64 \rightarrow 13}(9) = 0.57, r_{67 \rightarrow 34}(9) = 4.04$ $r_{80 \rightarrow 25}(9) = 2.04, r_{99 \rightarrow 20}(9) = 4.04$
10	$r_{6 \rightarrow 34}(10) = 3.56, r_{13 \rightarrow 56}(10) = 3.73, r_{20 \rightarrow 99}(10) = 2.20, r_{28 \rightarrow 39}(10) = 1.59, r_{34 \rightarrow 67}(10) = 5.60, r_{35 \rightarrow 84}(10) = 1.59$ $r_{39 \rightarrow 68}(10) = 1.02, r_{39 \rightarrow 64}(10) = 0.57, r_{48 \rightarrow 13}(10) = 1.59, r_{51 \rightarrow 99}(10) = 3.41, r_{51 \rightarrow 35}(10) = 1.59, r_{51 \rightarrow 20}(10) = 2.20$ $r_{64 \rightarrow 13}(10) = 1.59, r_{67 \rightarrow 76}(10) = 3.46, r_{67 \rightarrow 48}(10) = 1.59, r_{67 \rightarrow 13}(10) = 0.56, r_{68 \rightarrow 64}(10) = 1.02, r_{76 \rightarrow 56}(10) = 3.46$ $r_{84 \rightarrow 87}(10) = 1.59, r_{87 \rightarrow 28}(10) = 1.59, r_{99 \rightarrow 34}(10) = 2.04, r_{99 \rightarrow 6}(10) = 3.56$

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Appendix

Proof of Lemma 2 Our proof is based on contradiction. Assume that the number of linear segments that Algorithm 1 generates is K_l , and $s_l^{(k)}$, $k = 0, \dots, K_l$, are the corresponding X -axis values of the endpoints. Suppose that there is another piece-wise linear approximation that needs

$K'_l < K_l$ linear segments and $t_l^{(k)}$ s (with $k = 0, \dots, K_l$, $t_l^{(0)} = 0$ and $t_l^{(K_l)} = s_l^{\max}$) are the corresponding X -axis values of the endpoints.

Since $s_l^{(1)}$ is the largest X -axis value of the second endpoint, we have $t_l^{(1)} \leq s_l^{(1)}$. By induction, we can show that $t_l^{(k)} \leq s_l^{(k)}$, $k = 1, \dots, K'_l$. For $k = K'_l$, we have $t_l^{(K'_l)} \leq s_l^{(K'_l)}$. Further, since $K'_l < K_l$, we also have $s_l^{(K'_l)} < s_l^{\max}$. Therefore, we conclude that $t_l^{(K'_l)} \leq s_l^{(K'_l)} < s_l^{\max}$, which is a contradiction to $t_l^{(K'_l)} = s_l^{\max}$. This completes our proof. \square

Proof of Lemma 3 Note that the only difference between OPT and OPT-R is the link capacity constraints. Each link capacity constraint for link l in OPT is replaced by a set of linear constraints in OPT-R. Since these linear constraints are generated by the piece-wise linear segments lying beneath the log curve, the feasible region of OPT-R falls inside in the feasible region of OPT. Thus, a feasible solution to OPT-R is also a feasible solution to OPT. \square